



# Free-viewpoint Immersive Networked Experience

## D6.3 Free-viewpoint video player

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## **1 Introduction**

The purpose of this document is to describe the second version of the free-viewpoint video player prototype as in WP6.

For this deliverable Bitmanagement has developed the second version of the fine free viewpoint video player according to WP 6 Task 1 as a multi-view compliant player that enables both photorealistic as well as 3D rendering. APIs to plug-into Bitmanagement's BS Contact player, new media decoders and network interfaces for fine particular applications, e.g. video streaming have been developed in order to cover the needs from other related work packages, especially WP6 and WP4. This has been done according to the requirements described in deliverable 2.2. Test data for video mesh generation from UPF and gesture reconstruction data from KTH has been visualized as well as a test system for computer graphics rendering has been developed. The following describes the results in rendering the diverse visualization needs of the project. The rendered output is visualized and described in brief for video depth maps, triangulation and the visualization of artificial computer graphic soccer avatars as well as the visualization of free viewpoint meshes from WP 4. The results are positive as the diverse rendering needs of the project have been addressed and implemented.

## ***2 Visualization of video depth maps and 3D triangulated meshes from video***



**Figure 2.1: Visualization of a 3D mesh from height-field data**

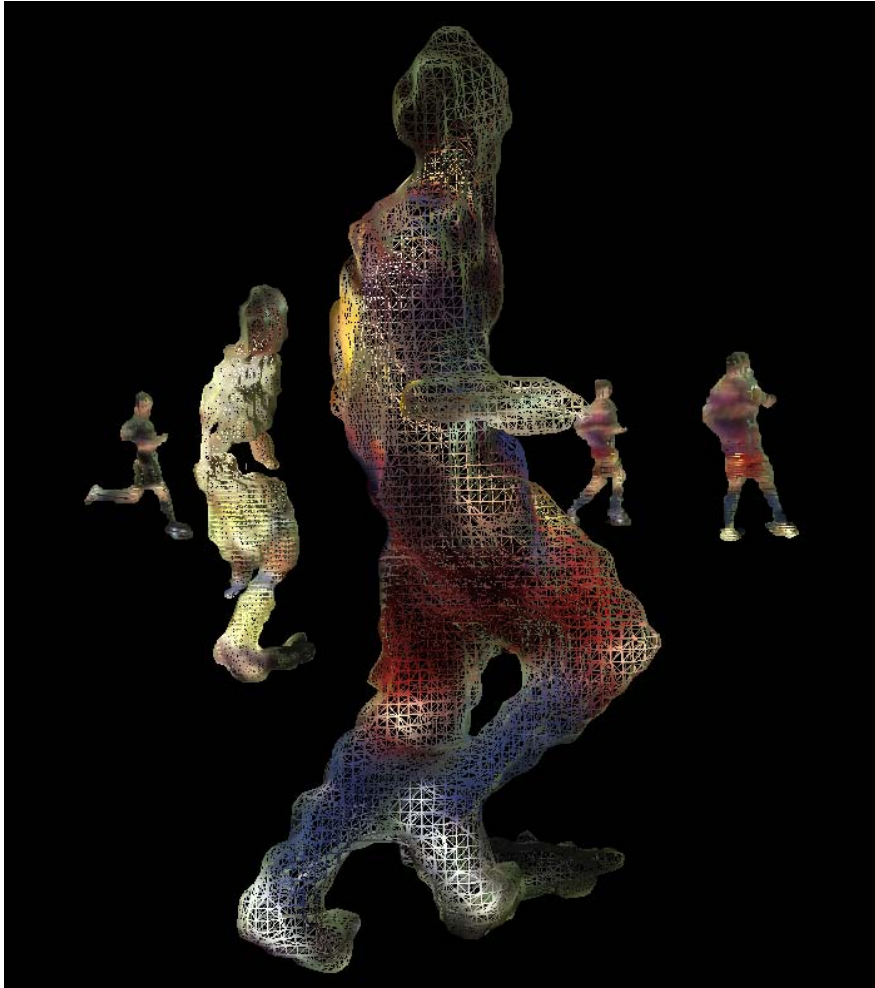
In addition to the ROI coded video sequences of deliverable 6.1 that resulted in a flat 2D video with alpha channel border cut inserted in a 3D environment Bitmanagement has developed a capability in the FINE player to visualize truly 3D avatars based on video textures and depth maps. From the live video feed and live depth map stream a triangulated mesh is constructed in real-time from a X3D height-field. The mesh shows 3D depth as well as accurate textures and is inserted in the 3D soccer scene as an object. The positions of the resulting 3D video avatar can be changed according to the real player positions of the soccer players supplied by the FINE multi-user server.

However the 3D mesh depends on the number of depth cameras viewing the scene. If one camera is used only as above the maximum viewpoint change may be a turn of about 30 degrees as an oval shape height-field (figure 2.1). The viewing experience can be enhanced if the oval shape height-field is inserted as a billboard object always turning towards the viewing position. The positions of the resulting 3D video avatar can be changed according to the real player positions of the soccer players supplied by the FINE multi-user server.



**Figure 2.2: Shaded 3D mesh with colour vertex information**

Meshes constructed from many cameras exhibit a round object that can be seen as avatars from any angle, such as the above 3D mesh supplied by UPF from WP4 to Bitmanagement. However this kind of data constructed from video feed frames result in very large 3D scenes for single images and is difficult to visualize in realtime with standard methods. Bitmanagement has developed a possibility to optimize the scene data as well as the rendering speed for real-time replay with intelligent geometry and texture coding from WP 5 based on the BS Contact 3D engine. Please see deliverable 5.4 for details.



**Figure 2.3: Highly detailed 3D mesh shape from one video frame**

### **3 Visualization of gestures in graphic soccer avatars with the H-ANIME Standard**

#### **Overview H-Anime**

H-Anime (Human Animation, [1]) is a standardized way for representing virtual humans. Virtual humans or Humanoids are often also referred to as Avatars. The H-Anime standard has advantages with regards to the simplicity of the animation of body parts of a virtual human being and the segmentation from the animation sequence and the modelling. An Avatar in H-Anime therefore consists of a set of segments (e.g. feet and hands) that are interconnected with joints (elbows, ankles). The angles of the joints can be changed according to the animation at runtime. The result is an animated avatar that moves the body parts according to an animation string made from angles.

#### **X3D and HTML5**

The implementation of the animated players in X3D with the H-Anim standard constitutes a transition path towards emerging technologies such as HTML 5 and WebGL rendering. First implementation with X3D in WebGL are using 3D renderers written in Javascript. The rendering speed of these Javascript implementations are still slow today compared to native C++ rendering. However there is a strong initiative to include X3D content into HTML 5, as the W3C consortium states that

*"Embedding 3D imagery into XHTML documents is the domain of X3D, or technologies based on X3D that are namespace-aware."* ([2])

Therefore the soccer avatar content in the Fine project represented in X3D is future prove and will inherit a long life time and compatibility from standardized formats.

KTH has supplied Bitmanagement with captured and reconstructed gesture data from their FINE research. The FINE player has been amended to support these gesture data. After modelling the avatar the data from optical tracking had to be translated in the ISO H-ANIME format to match the gestures with the body parts. The resulting scene has been ported into X3D binary for fast replay. The animation of the scene has been done by dynamic scripting in the X3D scene according to the H-Anime 1.1 Joint hierarchy. The X3D scene is now lively animated and can be used for simulating advanced running and jumping behaviour in the avatar.



```
PROTO Humanoid [  
  eventIn    SFFloat  set_fraction  
  eventIn    MFNode   set_joints  
  eventIn    MFNode   set_skeleton  
  eventIn    SFNode   set_skinCoord  
  field      SFVec3f  bboxCenter    0 0 0  
  field      SFVec3f  bboxSize      -1 -1 -1  
  field      MFNode   joints        []  
  field      MFNode   skeleton      []  
  field      SFNode   skinCoord     NULL  
  exposedField SFVec3f  center      0 0 0  
  exposedField MFString info        []  
  exposedField SFString name        ""  
  exposedField SFRotation rotation   0 0 1 0  
  exposedField SFVec3f  scale        1 1 1  
  exposedField SFRotation scaleOrientation 0 0 1 0  
  exposedField MFNode   segments    []  
  exposedField MFNode   sites       []  
  exposedField MFNode   skin        []  
  exposedField SFNode   skinNormal  NULL  
  exposedField SFVec3f  translation  0 0 0  
  exposedField SFString version     "2.0"  
  exposedField MFNode   viewpoints  []  
  eventOut   MFNode   joints_changed  
  eventOut   MFNode   skeleton_changed  
  eventOut   SFNode   skinCoord_changed  
]
```

**Figure 3.1: H-ANIME 1.1 compliant Humanoid proto**

```
// Transforms the vertices related to a joint
function Transform() {
    // Make sure that this is a joint
    var j;
    for (j=0; ((j<iNumJoints) && (joints[j].name != nextjoint.name)); j++);

    // If it is, we process the data
    if (j<iNumJoints) {
        // Read in current next joint
        var currentJoint = nextjoint;
        // Read in current matrix
        var currentMatrix = new VrmlMatrix();
        currentMatrix.setTransform(translation,
            rotation,
            scale,
            new SFRotation(1,0,0,0),
            new SFVec3f(0,0,0));
        // Create matrix corresponding to this joints transform
        var newMatrix = new VrmlMatrix();
        newMatrix.setTransform(currentJoint.translation,
            currentJoint.rotation,
            currentJoint.scale,
            currentJoint.scaleOrientation,
            currentJoint.center);
        // Update current matrix with matrix from this joint
        currentMatrix = newMatrix.multRight(currentMatrix);
        // Transform all vertices associated with this joint
        var iNumAffectedVertices = currentJoint.skinCoordIndex.length;
        var v;
        for (v=0; v<iNumAffectedVertices; v++) {
            var newVertex =
currentMatrix.multVecMatrix(coordList[currentJoint.skinCoordIndex[v]].multiply(currentJoint.skinCoord
Weight[v]));
            skinCoord.point[currentJoint.skinCoordIndex[v]] =
skinCoord.point[currentJoint.skinCoordIndex[v]].add(newVertex);
        }
        // Transform all children
        var children = currentJoint.children;
        var c;
        for (c=0; c<children.length; c++) {
            nextjoint = children[c];
            currentMatrix.getTransform(translation,rotation,scale);
            Transform();
        }
    }
}
```

**Figure 3.2: Transforming vertices related to a joint**



**Figure 3.3: Screenshot 1 from animated soccer player with advanced kicking gesture**



**Figure 3.4: Screenshot 2 from animated soccer player with advanced kicking gesture**



**Figure 3.5: Screenshot 3 from animated soccer player with advanced kicking gesture**



**Figure 3.6: Screenshot 1 from animated soccer player with advanced kicking gesture**

## **4 Conclusion**

The WP 6 T1 has implemented a multi-view compliant player with both photorealistic as well as computer graphics 3D rendering capabilities according to the needs of the project. The use of standardized 3D file-formats for 3D content of avatars is future prove and goes hand in hand with new emerging technologies in web based 3D graphics rendering.

## **5 Installation**

Please unzip the file "gesture\_recognition\_player\_scene" in the Fine Plone server and copy the data to your hard disc. Please install the BS Contact 3D engine, register it for x3d binary files and double click on the file "player\_on\_ground\_X3DB" in the directory "player\_scene" to start the animated 3d scene or use the file menu to load. You can change your viewpoint by holding the left mouse button down and move the mouse around the kicking avatar object.

## **5 References**

[1] H-ANIME Standard:  
Humanoid Animation Working Group of Web3D consortium  
<http://h-anim.org/>

[2] X3D and HTML5  
[http://www.web3d.org/x3d/wiki/index.php/X3D\\_and\\_HTML5](http://www.web3d.org/x3d/wiki/index.php/X3D_and_HTML5)